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Methods by which robots can learn control laws that enable real-time reactivity using dynamical systems; with applications and exercises. This book presents a wealth of machine learning techniques to make the control of robots more flexible and safe when interacting with humans. It introduces a set of control laws that enable reactivity using dynamical systems, a widely used method for solving

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motion-planning problems in robotics. These control approaches can replan in milliseconds to adapt to new environmental constraints and offer safe and compliant control of forces in contact. The techniques offer theoretical advantages, including convergence to a goal, non-penetration of obstacles, and passivity. The coverage of learning begins with low-level control parameters and progresses to higher-level competencies composed of combinations of skills. Learning for Adaptive and Reactive Robot Control is designed for graduate-level courses in robotics, with chapters that proceed from fundamentals to more advanced content. Techniques covered include learning from demonstration, optimization, and reinforcement learning, and using dynamical systems in learning control laws, trajectory planning, and methods for compliant and force control .

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Features for teaching in each chapter:

- applications, which range from arm manipulators to whole-body control of humanoid robots;
- pencil-and-paper and programming exercises;
- lecture videos, slides, and MATLAB code examples available on the author ' s website .
- an eTextbook platform website offering protected material[EPS2] for instructors including solutions.

Volume II of The Official History of the UK Strategic Nuclear Deterrent provides an authoritative and in-depth examination of the British government ' s strategic nuclear policy from 1964 to 1970. Written with full access to the UK documentary record, Volume II examines the controversies that developed over nuclear policy following the arrival in office of a Labour government led by Harold Wilson in October 1964 that openly questioned

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the independence of the deterrent. Having decided to preserve the Polaris programme, Labour ministers were nevertheless committed not to develop another generation of nuclear weapons beyond those in the pipeline, placing major doubts over the long-term future of the nuclear programme and collaboration with the United States. Defence planners also became increasingly concerned that the deployment of Soviet anti-ballistic missile (ABM) defences around Moscow threatened to undermine the ability of Polaris to fulfil its role as a national strategic nuclear deterrent. During 1967, under heavy pressures to control defence spending, a protracted debate was conducted within Whitehall over the future of Polaris and how to respond to the evolving ABM challenge. The volume concludes with Labour 's defeat at the general election of June 1970, by which

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time the Royal Navy had assumed the nuclear deterrent role from the RAF, and plans had already been formulated for a UK project to improve Polaris which could both ensure its continuing credibility and rejuvenate the Anglo-American nuclear relationship. This book will be of much interest to students of British politics, Cold War history, nuclear proliferation and international relations.

Ninth volume of a 40 volume series on nanoscience and nanotechnology, edited by the renowned scientist Challa S.S.R. Kumar. This handbook gives a comprehensive overview about Nanotechnology Characterization Tools for Tissue Engineering and Medical

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Therapy. Modern applications and state-of-the-art techniques are covered and make this volume an essential reading for research scientists in academia and industry.

This open access book bridges the gap between playing with robots in school and studying robotics at the upper undergraduate and graduate levels to prepare for careers in industry and research. Robotic algorithms are presented formally, but using only mathematics known by high-school and first-year college students, such as calculus, matrices and probability. Concepts and algorithms are explained through detailed diagrams and calculations. Elements of Robotics presents an overview of different types of robots and the components used to build robots, but focuses on robotic algorithms: simple algorithms like odometry and

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feedback control, as well as algorithms for advanced topics like localization, mapping, image processing, machine learning and swarm robotics. These algorithms are demonstrated in simplified contexts that enable detailed computations to be performed and feasible activities to be posed. Students who study these simplified demonstrations will be well prepared for advanced study of robotics. The algorithms are presented at a relatively abstract level, not tied to any specific robot. Instead a generic robot is defined that uses elements common to most educational robots: differential drive with two motors, proximity sensors and some method of displaying output to the user. The theory is supplemented with over 100 activities, most of which can be successfully implemented using inexpensive educational robots. Activities that require more computation can be

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programmed on a computer. Archives are available with suggested implementations for the Thymio robot and standalone programs in Python.

In the not-too-distant future, in what was once the old City of New York, megacorporations have taken over everything. Now even the internet is owned, and the only way to transmit sensitive information is by a network of highly skilled couriers called “ data runners ” who run it over the sneakernet. It is a dangerous gig in a dirty world, but Jack Nill doesn ’ t have much choice in the matter. A brilliant young math whiz and champion of parkour, Jack must become one of these data runners in order to get his father out of a major gambling debt. When a mysterious stranger loads Jack ’ s chip with a cryptic cargo that everybody wants, he soon becomes the key

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figure in a conspiracy that could affect the entire North American Alliance. Now it ' s all up to Jack. With the help of his best friend, Dexter, and a girl who runs under the name Red Tail, Jack will have to use all his skills to outrun the retrievers and uncover the truth before they catch him and clip him for good.

This textbook provides a coherent introduction to the main concepts and methods of one-parameter statistical inference. Intended for students of Mathematics taking their first course in Statistics, the focus is on Statistics for Mathematicians rather than on Mathematical Statistics. The goal is not to focus on the mathematical/theoretical aspects of the subject, but rather to provide an introduction to the subject tailored to the mindset and tastes of Mathematics students, who are sometimes

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turned off by the informal nature of Statistics courses. This book can be used as the basis for an elementary semester-long first course on Statistics with a firm sense of direction that does not sacrifice rigor. The deeper goal of the text is to attract the attention of promising Mathematics students.

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