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In 2006 , Murty proposed an interior point method for solving LP [1,2]. Each iteration in Murty ' s method consists of two steps ; a centering step and a descent step. The centering step is a corrector step [3] that tries to move a current interior feasible solution into the center of the feasible region without sacrificing the objective quality.

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Professor Murty teaches graduate and undergraduate courses in linear, integer and non-linear programming and network flows. His recent research includes studies in mathematical programming and its applications as well as research on optimization algorithms.

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The theory behind linear programming drastically reduces the number of possible solutions that must be checked. The linear programming problem was first shown to be solvable in polynomial time by Leonid Khachiyan in 1979, [5] but a larger theoretical and practical breakthrough in the field came in 1984 when Narendra Karmarkar introduced a new interior-point method for solving linear-programming problems.

Linear programming - Wikipedia

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A comprehensive, up-to-date text on linear programming. Covers all practical modeling, mathematical, geometrical, algorithmic, and computational aspects. Surveys recent developments in the field, including the Ellipsoid method. Includes extensive examples and exercises. Designed for advanced undergraduates or graduates majoring in engineering, mathematics, or business administration.

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$K(M)$ The union of all complementary cones in $C(M)$. It is the set of all vectors q for which the LCP (q, M) has at least one solution. $Z(y), W(y)$ If $y = (y_1, \dots, y_n)^T$ is a complementary vector for the LCP (q, M) of order n , then $Z(y) = \{j : y_j = z_j\}$ and $W(y) = \{j : y_j = w_j\}$.

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Linear complementarity, linear and nonlinear programming ...

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A hyperplane in R^n is the set of feasible solutions of a single linear equation. Let $H = \{ x : a_1 x_1 + \dots + a_n x_n = a_0 \}$, where the coefficient vector $(a_1, \dots, a_n) \neq 0$, be a hyperplane ...

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